# Short-time inertial response of viscoelastic fluids measured with Brownian motion and with active probes

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We have directly observed short-time stress propagation in viscoelastic fluids using two optically trapped particles and a fast interferometric particle-tracking technique. We have done this both by recording correlations in the thermal motion of the particles and by measuring the response of one particle to the actively oscillated second particle. Both methods detect the vortexlike flow patterns associated with stress propagation in fluids. This inertial vortex flow propagates diffusively for simple liquids, while for viscoelastic solutions the pattern spreads superdiffusively, depending on the shear modulus of the medium.

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# I. INTRODUCTION

Motion in simple liquids at small scales is usually characterized by low Reynolds numbers, in which the response of a liquid to a force applied at one point is Stokes-likedecaying with distance r as 1/r away from the origin of the disturbance [1–3]. Here, fluid inertia can be neglected, and the force is effectively felt instantaneously everywhere within the medium. In practice, this is a good approximation, for instance, in water at the colloidal scale up to micrometers on time scales larger than a microsecond. At short times or high frequencies, however, fluid inertia limits the range of stress propagation. Any instantaneous disturbance must be confined to a small region for short times. If the medium is also incompressible, then this naturally gives rise to vorticity and backflow. In simple liquids, stress then propagates through the diffusive spreading of this vortex. Although this basic physical picture has been known theoretically for simple liquids since the work of Oseen in 1927 [4] and has been shown in computer simulations since the 1960s [5]. experimental observation of these effects has been largely indirect, for instance, in the form of short-time corrections to Brownian motion [6]. Direct experimental observation has only recently been possible because of the high temporal and spatial resolution required [7].

The finite time it takes for vorticity to propagate leads to persistence of fluid motion that manifests itself in algebraic decay of the autocorrelation function of the velocity of either a fluid element or a particle embedded in the fluid. This decay is slower than the naive expectation of exponentially decaying correlations for a massive particle experiencing viscous drag. Thus, the effect is known as the long-time tail effect [6,8,9], which characterizes the transition from ballistic to Brownian motion of particles in simple liquids. This effect has been shown to be present even at the atomic level, e.g., from neutron scattering experiments on liquid sodium [10].

We have shown that the interparticle correlations and response functions of two particles can be used to directly resolve the flow pattern and dynamics of vortex propagation [7,11]. This was done by measuring the correlated thermal motion of two optically trapped spherical particles using an interferometric technique [12,13] with high temporal (up to 100 kHz) and spatial (subnanometer) resolution in both viscous and viscoelastic fluids. We were able to observe, for instance, the anticorrelation in the interparticle fluctuations of thermal motion that is characteristic of the vortex propagation. The method is related to passive two-particle microrheology [14-19] which can be used to measure shear elastic moduli of viscoelastic materials. However, as the present results show, inertial effects can severely limit the practical high-frequency range of such two-particle microrheology techniques, which have so far neglected inertia.

The interparticle response functions  $\alpha(\omega)$ , with real  $(\alpha')$ and imaginary  $(\alpha'')$  parts defined by  $\alpha(\omega) = \alpha'(\omega) + i\alpha''(\omega)$ , are obtained for motion parallel ( $\alpha_{\parallel}$ ) and perpendicular ( $\alpha_{\perp}$ ) to the center line connecting the two particles. In the passive approach, we directly measure the imaginary part of the response function from the thermal position fluctuations of the two particles via the fluctuation-dissipation theorem (FDT). The real part of the response function is then obtained from a Kramers-Kronig integral [20].

Here, in order to directly measure both real (in-phase) and imaginary (out-of-phase) parts of the response function, we have developed an active method [21,22], in which one optical trap drives oscillatory motion of one particle, while the response of a second particle is measured at separation r. We present and compare detailed experimental results of both passive and active approaches. We also present a theoretical derivation of the predicted response functions and corresponding algebraic decay of the velocity autocorrelation functions for viscoelastic fluids.

The outline of the paper is as follows. In Sec. II, we present the theoretical analysis. In Sec. III, we present the materials and methods of sample preparation, as well as the experimental techniques for the passive and active measurements of the response functions. In Sec. IV we describe our methods of data analysis used for the results presented in Sec. V. In Sec. V, we first compare the data for simple liquids with the dynamic Oseen tensor, which demonstrates the diffusive propagation of the vortex flow. We then present our results and comparison with theory for viscoelastic solutions, including the evidence for superdiffusive stress propagation. Finally, we conclude with a discussion (Sec. VI), also mentioning implications of our results for microrheology in general.

## **II. THEORY AND BACKGROUND**

Newtonian liquids are described by the Navier-Stokes equation, which is nonlinear. The nonlinearity, however, can usually be neglected either for small distances or for low velocities [1,2]. This is the so-called low-Reynolds-number regime, since the relative importance of nonlinearities is characterized by the Reynolds number  $\text{Re}=\frac{UL\rho}{\eta}$ , where  $U, L, \rho$ , and  $\eta$  are, respectively, the characteristic velocity and length scales, the density, and the viscosity. For steady flow, this regime can also be thought of as the noninertial regime, in which stress propagates instantaneously and, for instance, the velocity response at a distance *r* from a point force varies as 1/r [1–3]. Such *Stokes* flow accurately describes the motion of micrometer-sized objects in water on time scales longer than a few microseconds.

Even at low Reynolds number, however, there are remaining consequences of fluid inertia for nonstationary flows [3]. This *unsteady Stokes* approximation is described by the linearized Navier-Stokes equation

$$\rho \frac{\partial}{\partial t} \vec{v} = \eta \nabla^2 \vec{v} - \vec{\nabla} P + \vec{f}, \qquad (1)$$

where  $\vec{v}$  is the velocity field, *P* is the pressure that enforces the incompressibility of the liquid, and  $\vec{f}$  is the force density *applied* to the fluid. By taking the curl of this equation we observe that the vorticity  $\vec{\Omega} = \vec{\nabla} \times \vec{v}$  satisfies the diffusion equation with diffusion constant  $\nu = \eta / \rho$ .

As noted above, the short-time response of a liquid to a point force generates a vortex. The propagation of stress away from the point disturbance is diffusive: after a time *t*, this vortex expands away from the point force to a size of order  $\delta \sim \sqrt{\eta t/\rho}$ . This can be seen by the fact that the curl of Eq. (1) resembles the diffusion equation in the absence of forces. In the wake of this moving vortex is the usual Stokes flow that corresponds to a 1/r dependence of the velocity field. For an oscillatory disturbance at frequency  $\omega$ , the propagation of vorticity defines a *penetration depth*  $\delta \sim \sqrt{\eta/(\omega\rho)}$  [1]. Stress effectively propagates instantaneously on length scales shorter than this.

This picture generalizes to the case of homogenous *vis*coelastic media characterized by an isotropic, timedependent shear modulus G(t) [23], although the propagation of stress generally becomes superdiffusive [11]. We further assume that the medium is incompressible, which is a particularly good approximation for polymer solutions such as those considered here, at least at high frequencies [20,24,25]. The deformation of the medium is characterized by a *local* displacement field  $\vec{u}(\vec{r},t)$ , and the viscoelastic analog of the Navier-Stokes equation (1) is

$$\rho \frac{\partial^2}{\partial t^2} \vec{u}(\vec{r},t) = \vec{\nabla} \cdot \vec{\boldsymbol{\sigma}}(\vec{r},t) - \vec{\nabla}P + \vec{f}(\vec{r},t), \qquad (2)$$

where

$$\vec{\boldsymbol{r}}(\vec{r},t) = 2 \int_{-\infty}^{t} dt' G(t-t') \, \vec{\boldsymbol{\gamma}}(\vec{r},t') \tag{3}$$

is the local stress tensor and

$$\vec{\gamma} = \frac{1}{2} [\vec{\nabla} \vec{u} + (\vec{\nabla} \vec{u})^{\dagger}]$$
(4)

is the local deformation tensor. Incompressibility corresponds to the constraint  $\nabla \cdot \vec{u} = 0$ . In the limit of an elastic medium with shear modulus *G*, for which the constitutive relation in Eq. (3) becomes  $\vec{\sigma} = [\nabla \vec{u} + (\nabla \vec{u})^{\dagger}]$ , we obtain the wave equation from the curl of Eq. (2), which results in stress propagation with a constant velocity. This suggests that the propagation of stress for viscoelastic media is super-diffusive, as we derive below.

Equations (2) and (3) can be simplified by a decomposition of the force density and deformation into Fourier components. Taking spatiotemporal Fourier transforms defined as

$$\vec{u}(\vec{k},\omega) = \int d^3r \int_{-\infty}^{\infty} dt \ e^{i(\omega t - \vec{k} \cdot \vec{r})} \vec{u}(\vec{r},t),$$
(5)

and defining the complex modulus

$$G^{\star}(\omega) \equiv G'(\omega) + iG''(\omega) = \int_0^{\infty} dt \ e^{i\omega t} G(t), \qquad (6)$$

we can eliminate the pressure by imposing incompressibility in Eqs. (2) and (3). This leads to

$$\vec{u}(\vec{k},\omega) = \left(\frac{1-\hat{k}\hat{k}}{G^{\star}(\omega)k^2 - \rho\omega^2}\right) \cdot \vec{f}(\vec{k},\omega), \tag{7}$$

where  $\hat{k} = \vec{k}/|k|$ . We invert this Fourier transform to obtain the displacement response function due to a point force applied at the origin.

#### A. Response functions

For a point force f at the origin, the linear response of the medium at  $\vec{r}$  is given by a tensor  $\alpha_{ij}$ , where  $u_i(\vec{r}, \omega) = \alpha_{ij}(\vec{r}, \omega)f_j(\vec{0}, \omega)$ . Here,  $\alpha_{ij} = \alpha'_{ij} + i\alpha''_{ij}$  is, in general, complex. Given our assumptions of rotational and translational symmetry, there are only two distinct components of the response. These are (1) a *parallel* response that is given by a displacement field  $\vec{u}$  parallel to both  $\vec{f}$  and  $\vec{r}$ , and (2) a *perpendicular* response given by  $\vec{u}$  parallel to  $\vec{f}$  and perpendicular to  $\vec{r}$ . The parallel response function  $\alpha_{\parallel}$ , for instance, is

obtained from the inverse Fourier transform of Eq. (7) [11]. The response functions for general  $G^*(\omega)$  are given by

$$\alpha_{\parallel}(r,\omega) = \alpha_{\parallel}' + i\alpha_{\parallel}'' = \frac{1}{4\pi G^{\star}(\omega)r}\chi_{\parallel}(r\sqrt{\kappa})$$
(8)

and

$$\alpha_{\perp}(r,\omega) = \alpha'_{\perp} + i\alpha''_{\perp} = \frac{1}{8\pi G^{\star}(\omega)r}\chi_{\perp}(r\sqrt{\kappa}), \qquad (9)$$

where  $\kappa = \rho \omega^2 / G^*(\omega)$  is complex,

$$\chi_{\parallel}(x) = \frac{2}{x^2} [(1 - ix)e^{ix} - 1], \qquad (10)$$

and

$$\chi_{\perp}(x) = \frac{2}{x^2} [1 + (x^2 - 1 + ix)e^{ix}].$$
(11)

The magnitude of  $\kappa$  defines the inverse (viscoelastic) penetration depth

$$\delta_{ve} = \sqrt{\frac{|G^{\star}|}{\rho\omega^2}}.$$
 (12)

## 1. Simple liquids

For a simple liquid,  $G^*(\omega) = -i\omega\eta$  and  $\kappa = i\rho\omega/\eta$ . The velocity response of the liquid is then characterized by

$$-i\omega\alpha_{\parallel}(r,\omega) = \omega\alpha_{\parallel}'' - i\omega\alpha_{\parallel}' = \frac{1}{4\pi\eta r}\widetilde{\chi}_{\parallel}\left(r\sqrt{\frac{\rho\omega}{2\eta}}\right) \quad (13)$$

and

$$-i\omega\alpha_{\perp}(r,\omega) = \omega\alpha_{\perp}'' - i\omega\alpha_{\perp}' = \frac{1}{8\pi\eta r}\tilde{\chi}_{\perp}\left(r\sqrt{\frac{\rho\omega}{2\eta}}\right),$$
(14)

where

$$\tilde{\chi}'_{\parallel}(x) = \frac{[(1+x)\sin x - x\cos x]e^{-x}}{x^2},$$
(15)

$$\tilde{\chi}_{\parallel}''(x) = \frac{1 - [(1+x)\cos x + x\sin x]e^{-x}}{x^2},$$
(16)

$$\tilde{\chi}_{\perp}'(x) = \frac{[(x+2x^2)\cos x - (1+x)\sin x]e^{-x}}{x^2}, \qquad (17)$$

$$\tilde{\chi}_{\perp}''(x) = \frac{[(x+2x^2)\sin x + (1+x)\cos x]e^{-x} - 1}{x^2}.$$
 (18)

Thus, for instance, the in-phase and out-of-phase velocity responses in the parallel direction are given by  $\omega \alpha'' = \frac{1}{4\pi \pi pr} \tilde{\chi}'_{\parallel}$  and  $-\omega \alpha' = \frac{1}{4\pi \pi pr} \tilde{\chi}''_{\parallel}$ .



FIG. 1. Comparison of theoretical and experimentally measured response functions for a simple liquid. The predictions of the normalized velocity field from the dynamic Oseen tensor in Eqs. (13) and (14) are shown as black and gray lines. Normalized complex interparticle response functions between two probe particles (silica beads,  $R=0.58 \ \mu\text{m}$ ) measured with the active microrheology method in water: (a)  $4\pi r \eta \omega \alpha_{\parallel}$  in the parallel direction and (b)  $8\pi r \eta \omega \alpha_{\perp}$  in the perpendicular direction, plotted versus the ratio of the separation distance *r* (fixed for a given bead pair,  $r=11.3 \ \mu\text{m}$  for parallel, and  $r=10.3 \ \mu\text{m}$  for perpendicular) to the frequency-dependent viscous penetration depth  $\delta_v$ . Both real (filled symbols) and imaginary parts (open symbols) are shown, for both parallel and perpendicular directions. These results are compared with the theory for  $\eta=0.97$  mPa s and  $\rho=1000 \ \text{kg m}^{-3}$ . There is good agreement with no free parameters.

We have written the response functions in Eqs. (8) and (9) in a form in which the noninertial limits  $(x \rightarrow 0)$  are simple:  $\chi_{\parallel,\perp} \rightarrow 1$ . Thus, for a simple liquid in the limit  $x \rightarrow 0$ , Eqs. (13) and (14) reduce to the (time-independent) Oseen tensor [2,4]. For finite *x*, these response functions give the dynamic Oseen tensor [4,26], which are shown as the solid lines in Fig. 1, where for small  $r/\delta$  the parallel and perpendicular *velocity* response (i.e.,  $-i\omega\alpha_{\parallel,\perp}$ ) approach  $\frac{1}{4\pi\eta r}$  and  $\frac{1}{8\pi\eta r}$  for a unit force at the origin. These then decay for  $r \ge \delta$ . The region of negative response in the perpendicular case corresponds to the backflow of the vortex.

The response functions above represent the ensembleaverage displacements due to forces acting in the medium. These response functions also govern the equilibrium thermal fluctuations and the correlated fluctuations from point to point within the medium. The relationship between thermal fluctuations and response is described by the fluctuationdissipation theorem. Specifically, for points separated by a distance r along the  $\hat{x}$  direction,

$$C_{\parallel,\perp}(r,\omega) = \frac{2k_B T}{\omega} \alpha_{\parallel,\perp}''(r,\omega), \qquad (19)$$

where

$$C_{\parallel}(r,\omega) = \int_{-\infty}^{\infty} dt \ e^{i\omega t} \langle u_x(0,0)u_x(r,t) \rangle$$
(20)

and

$$C_{\perp}(r,\omega) = \int_{-\infty}^{\infty} dt \ e^{i\omega t} \langle u_{y}(0,0)u_{y}(r,t) \rangle.$$
(21)

#### 2. Polymer solutions

An experimentally pertinent illustration is given by the *high-frequency* complex shear modulus of a polymer solution,

$$G^{\star}(\omega) = -i\omega\eta + \overline{g}(-i\omega)^{z} = |G|e^{-i\psi}$$
(22)

which has both solvent and polymer contributions. For the Rouse model of flexible polymers z=1/2 [27], while for semiflexible polymers z=3/4 [20,28,29]. The latter case is shown as the solid lines in Fig. 2. We see that the oscillatory or anticorrelated response becomes more pronounced in viscoelastic materials.

The magnitude of the complex modulus is given by

$$|G| = \sqrt{(\overline{g}\omega^z)^2 + (\omega\eta)^2 + 2\omega^{z+1}\eta\overline{g}\sin(\pi z/2)}, \qquad (23)$$

while its phase is given by

$$\sin \psi = \frac{\left[\omega \eta + \bar{g}\omega^z \sin(\pi z/2)\right]}{|G|}$$
(24)

and

$$\cos \psi = \frac{\overline{g}\omega^z \cos(\pi z/2)}{|G|}.$$
 (25)

It is also useful to have the following expressions for the half phase-angles:

$$\sin\frac{\psi}{2} = \sqrt{\frac{1}{2}} \left(1 - \frac{\overline{g}\omega^z \cos(\pi z/2)}{|G|}\right),\tag{26}$$

$$\cos\frac{\psi}{2} = \sqrt{\frac{1}{2}\left(1 + \frac{\overline{g}\omega^z \cos(\pi z/2)}{|G|}\right)}.$$
 (27)

We define the real parameter  $\beta = r \sqrt{\rho \omega^2 / |G|}$  and use the definitions Eqs. (10) and (11) to obtain the following compact expressions for the response functions  $(\alpha_{\perp}, \alpha_{\parallel})$  which can be expanded using the compound angle formulae and the definitions above. The real and imaginary parts of the parallel response are given by



FIG. 2. Comparison to Eqs. (8)–(11) of both real and imaginary parts of the normalized interparticle response functions between two probe particles (silica beads,  $R=0.58 \mu m$ ), measured with the active microrheology method for two separation distances r in 1 mg/ml entangled F-actin solutions. (a)  $4\pi r |G| \alpha_{\parallel}(\omega)$  and (b)  $8\pi r |G|\alpha_{\perp}(\omega)$ , plotted versus the ratio of the separation distance r ( $r=11.3 \ \mu m$  in parallel and  $r=10.3 \ \mu m$  in perpendicular direction) to the frequency-dependent viscoelastic penetration depth  $\delta_{ve}$ . Here, the parameters  $\overline{g}$  and z in Eq. (22) were varied to obtain simultaneous fits of all data sets to Eqs. (28)-(31), using a single set of parameters z and  $\overline{g}$ , while accounting for the solvent (water) viscosity. Both the real (filled symbols) and imaginary (open symbols) parts of both parallel and perpendicular response functions are in good agreement with Eqs. (28)–(31) with optimal parameters  $\overline{g}$  $=0.22\pm0.05$  Pa s<sup>z</sup> and  $z=0.78\pm0.02$ . The corresponding theoretical lines are shown for z=0.75 and  $\overline{g}=0.22$ .

$$4\pi |G| r\alpha'_{\parallel}(r,\omega) = \frac{2}{\beta^2} \left\{ e^{-\beta \sin \psi/2} \left[ \cos\left(\beta \cos \frac{\psi}{2}\right) + \beta \sin\left(\frac{\psi}{2} + \beta \cos\frac{\psi}{2}\right) \right] - 1 \right\}$$
(28)

and

$$4\pi |G| r \alpha''_{\parallel}(r,\omega) = \frac{2}{\beta^2} e^{-\beta \sin \psi/2} \left[ \sin\left(\beta \cos\frac{\psi}{2}\right) -\beta \cos\left(\frac{\psi}{2} + \beta \cos\frac{\psi}{2}\right) \right], \quad (29)$$

while the corresponding expressions for the perpendicular response are given by

$$8\pi |G| r \alpha'_{\perp}(r, \omega) = \frac{2}{\beta^2} \Biggl\{ 1 - e^{-\beta \sin \psi/2} \Biggl[ \cos \Biggl(\beta \cos \frac{\psi}{2} \Biggr) + \beta \sin \Biggl( \frac{\psi}{2} + \beta \cos \frac{\psi}{2} \Biggr) - \beta^2 \cos \Biggl( \psi + \beta \cos \frac{\psi}{2} \Biggr) \Biggr] \Biggr\}$$
(30)

and

$$8\pi |G| r \alpha_{\perp}''(r, \omega) = \frac{2}{\beta^2} e^{-\beta \sin \psi/2} \left[ -\sin\left(\beta \cos \frac{\psi}{2}\right) + \beta \cos\left(\frac{\psi}{2} + \beta \cos \frac{\psi}{2}\right) + \beta^2 \sin\left(\psi + \beta \cos \frac{\psi}{2}\right) \right].$$
(31)

The imaginary part of the response functions will be used to calculate the correlation functions, Eq. (19), used for analysis of the passive experiments, while the real part of the response functions will be used for comparison with the active experiments.

We can simplify the expressions above in the limit that the polymer contribution to the viscoelasticity dominates the shear modulus. We then obtain the simple scaling form  $G^{\star}(\omega) \simeq \overline{g}(-i\omega)^{z}$  [30] giving  $|G| = \overline{g}|\omega|^{z}$ ,  $\psi = \pi z/2$ . Further simplification of Eq. (19) using the expressions in Eqs. (31) and (29) and definitions in Eqs. (10) and (11) leads, e.g., to

$$C_{\parallel}(r,\omega) = \frac{k_B T}{2\pi\omega|G|r} \left(\frac{2}{\beta^2} e^{-\sin(z\pi/4)\beta} \left\{ \left[1 + \sin\left(\frac{z\pi}{4}\right)\beta\right] \times \sin\left[\cos\left(\frac{z\pi}{4}\right)\beta\right] - \cos\left(\frac{z\pi}{4}\right) \right] \times \beta \cos\left[\cos\left(\frac{z\pi}{4}\right)\beta\right] - \cos\left(\frac{z\pi}{4}\right) \right\} \right\},$$
(32)

where  $\beta = r \sqrt{\rho \omega^2} / |G|$  characterizes the overall decay of stress due to inertia. This decay corresponds to superdiffusive propagation of stress for viscoelastic media with  $G \sim \omega^z$  and z < 1, since the response is limited to a spatial range that grows with time as  $t^{(2-z)/2}$ . As noted above, for viscous media with z=1, the vorticity satisfies the diffusion equation, and the stress propagates diffusively, as  $t^{1/2}$ . In the elastic limit with z=0, by contrast, the corresponding equation becomes the wave equation, with ballistic propagation of stress. Viscoelastic media lead to intermediate, strictly superdiffusive behavior.

The resulting displacement field, exhibiting the vortex pattern, is shown in Fig. 3 for a point force at the origin pointed along the x axis. This flow pattern exhibits specific inversion symmetries:  $v_x (v_y)$  is symmetric (antisymmetric) for either  $x \rightarrow -x$  or  $y \rightarrow -y$ , as can be seen by the fact that the (linear) response must everywhere reverse if the direction of the force is reversed.



FIG. 3. Displacement field displays a clear vortexlike structure. Here, a force in the  $\hat{x}$  direction is applied at the origin (as shown by the filled circle and arrow). Distances are shown in units of the penetration depth  $\delta = \sqrt{|G|/(\rho\omega^2)}$ . This example has been calculated for the Rouse model with z=1/2.

#### B. Velocity autocorrelations and the long-time tail

The self-sustaining backflow represented in Fig. 3 gives rise to long-lived correlations that, for instance, affect the crossover from ballistic to diffusive motion of a particle in a liquid. For a simple liquid, the fluid velocity (auto)correlations  $\langle \vec{v}(0,t) \cdot \vec{v}(0,0) \rangle$  decay proportionally to  $\sim |t|^{-3/2}$ . This is known as the *long-time tail* [5,6,8]. For a viscoelastic fluid, stress propagation is faster than diffusive, resulting in a more rapid decay of velocity correlations. The decay is, however, still algebraic.

## 1. Simple liquids

For a simple liquid, Eq. (1) means that

$$(-i\omega\rho + \eta k^2)v_i = (\delta_{ij} - \hat{k}_i \hat{k}_j)f_j$$
(33)

for the Fourier transforms. This gives the response *in velocity*  $v_i$  to a force component  $f_j$  that is (thermodynamically) conjugate to a displacement  $u_j$ . We denote this response function by  $\chi_{v,u}$ , where

$$\chi_{v_i u_j}(\vec{k}, \omega) = \frac{(\delta_{ij} - \hat{k}_i \hat{k}_j)}{\eta k^2 - i\omega \rho}.$$
(34)

The fluctuation-dissipation theorem then tells us that

$$\chi_{v_i u_j}(\vec{r}, t) = -\frac{1}{kT} \frac{d}{dt} \langle v_i(\vec{r}, t) u_j(0, 0) \rangle, \qquad (35)$$

where this is valid only for t>0 because of causality in the response. The correlation function is, however, defined for both positive and negative times.

Due to translation invariance in time, the correlation function  $\langle v_i(\vec{r},t+t')u_i(0,t')\rangle$  must be independent of t'. Thus,

$$0 = \frac{d}{dt'} \langle v_i(\vec{r}, t+t') u_j(0, t') \rangle$$
$$= \langle \dot{v}_i(\vec{r}, t+t') u_j(0, t') \rangle + \langle v_i(\vec{r}, t+t') v_j(0, t') \rangle, \quad (36)$$

which also means that

$$kT\chi_{v_iu_i}(\vec{r},t)\rangle = \langle v_i(\vec{r},t)v_j(0,0)\rangle.$$

Again, this is valid only for t > 0 because of causality in the response. Ultimately, however, we are interested in the autocorrelation function  $\langle \vec{v} \cdot \vec{v} \rangle = \langle v_i v_i \rangle$  for  $r \rightarrow 0$  above. In this case, the correlation function is manifestly symmetric in *t*. Thus,

$$\langle v_i(\vec{r} \to 0, t) v_i(0, 0) \rangle = kT \chi_{v_i u_i}(\vec{r} \to 0, |t|).$$
 (37)

We first calculate  $\chi_{v_i u_j}(\vec{k}, t)$ , since the limit  $\chi_{v_i u_j}(\vec{r} \to 0, t)$  can be obtained from this simply by integrating over all  $\vec{k}$ ,

$$\begin{split} \chi_{v_i u_j}(\vec{k},t) &= (\delta_{ij} - \hat{k}_i \hat{k}_j) \int \frac{d\omega}{2\pi} e^{-i\omega t} \frac{1}{\eta k^2 - i\omega \rho} \\ &= \frac{(\delta_{ij} - \hat{k}_i \hat{k}_j)}{-2\pi i \rho} \int e^{-i\omega t} \frac{d\omega}{\omega + i\nu k^2}, \end{split}$$

where  $\nu = \eta / \rho$ . But, the last integral can depend only on the combination  $t\nu k^2$ , since we can replace  $\omega$  by  $\zeta \nu k^2$ , where  $\zeta$  is dimensionless. Specifically,

$$\chi_{\nu_i u_j}(\vec{k},t) = \frac{(\delta_{ij} - \hat{k}_i \hat{k}_j)}{-2\pi i \rho} \int e^{-i\zeta \nu k^2 t} \frac{d\zeta}{\zeta + i} = \frac{(\delta_{ij} - \hat{k}_i \hat{k}_j)}{\rho} e^{-\nu k^2 t}$$
(38)

for t > 0. Otherwise, the result is zero. This integral can be done by integration along a closed contour containing the real line in either the upper half plane for t < 0, or the lower half plane for t > 0.

Finally, to get the limit

$$\chi_{v_i u_i}(\vec{r} \to 0, t) \tag{39}$$

we simply integrate:

$$\chi_{\nu_i \mu_i}(\vec{r} \to 0, t) = \int \frac{d^3k}{(2\pi)^3} \frac{(\delta_{ii} - \hat{k}_i \hat{k}_i)}{\rho} e^{-\nu k^2 t} = \frac{2}{\rho} (4\pi\nu t)^{-3/2}.$$
(40)

Again, this is only for t > 0. Thus,

$$\langle \vec{v}(\vec{r} \to 0, t) \cdot \vec{v}(0, 0) \rangle = \frac{2kT}{\rho} (4\pi\nu|t|)^{-3/2}.$$
 (41)

#### 2. Viscoelastic media

For viscoelastic media, the calculation is similar, except that

$$\chi_{v_i u_j}(\vec{k}, \omega) = -i\omega\chi_{u_i u_j}(\vec{k}, \omega) = \chi_{v u}(\vec{k}, \omega)(\delta_{ij} - \hat{k}_i \hat{k}_j), \quad (42)$$

where  $\chi_{u_i u_i} = \alpha_{ij}$ , and where we have defined

$$\chi_{vu}(\vec{k},\omega) = \frac{1}{\rho} \left( \frac{i\omega}{\omega^2 - G^* k^2 / \rho} \right)$$
(43)

for simplicity. As above, all the singularities in this must lie in the lower half plane in order for the response function to be causal.

Evaluation of the inverse Fourier transform of Eq. (43) to obtain  $\chi_{vu}(\vec{k},t)$  can be done by use of the Mittag-Leffler functions. The Mittag-Leffler functions [31,32]  $E_{\alpha}(z)$ , which are entire functions parametrized by a continuous parameter  $\alpha$ , can be defined by the power series

$$E_{\alpha}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(1+\alpha k)}, \quad \alpha > 0.$$
(44)

Note that  $E_1(x) = \exp(x)$ . Straightforward manipulation [31] of the definition Eq. (44) shows that their causal Fourier transforms are given by

$$\int_{-\infty}^{\infty} dt \ e^{i\omega t} \Theta(t) E_{\alpha}(-at^{\alpha}) = \frac{i\omega}{\omega^2 - a(-i\omega)^{2-\alpha}}, \qquad (45)$$

where  $\Theta(t)$  is the Heaviside step function. Performing the inverse Fourier transform, we obtain

$$\chi_{vu}(\vec{k},t) = E_{2-z}[-(\bar{g}k^2/\rho)t^{2-z}], \quad t > 0,$$
(46)

for  $G^* = \overline{g}(-i\omega)^z$ . The asymptotic expansions for the Mittag-Leffler functions [31,33] are

$$E_{\alpha}(-z) = \begin{cases} 1 - \frac{z}{\Gamma(1+\alpha)} + O(z^2), & z \ll 1, \\ \frac{z^{-1}}{\Gamma(1-\alpha)} + O(z^{-2}), & z \gg 1. \end{cases}$$
(47)

Thus, the velocity correlation function is given by

$$\langle \vec{v}(\vec{r} \to 0, t) \cdot \vec{v}(0, 0) \rangle = \frac{2kT}{\rho} \frac{4\pi}{(2\pi)^3} \int_0^{1/a} k^2 dk E_{2-z} \\ \times [-(\bar{g}k^2/\rho)|t|^{2-z}].$$
(48)

From the asymptotic properties of  $E_{\alpha}(t)$ , it is clear that the integral does not converge at  $k \rightarrow \infty$ , necessitating a finite cutoff (which we choose as the size of the probe particle). We can express the correlation function as

$$\langle \vec{v}(0,t) \cdot \vec{v}(0,0) \rangle = |t|^{-3/2(2-z)} \frac{2kT}{\rho} \left(\frac{\rho}{\overline{g}}\right)^{3/2} \frac{2-z}{(2\pi)^2} I_{2-z},$$

$$I_{\alpha} = \int_{0}^{\Lambda_{\alpha}} dx \, x^{3\alpha/2-1} E_{\alpha}(-x^{\alpha}),$$

$$(49)$$

and  $\Lambda_{\alpha} = (|t|\overline{g}/\rho a^2)^{1/\alpha}$ .

We can get an approximation to the value of  $I_{\alpha}$  by splitting the integral into two sections,

$$I_{\alpha} = \int_{0}^{1} dx \ E_{\alpha}^{\ll}(-x^{\alpha}) + \int_{1}^{\Lambda_{\alpha}} dx \ E_{\alpha}^{\gg}(-x^{\alpha}),$$

using the two asymptotic forms for  $E_{\alpha}(t)$ . We then obtain finally the expression

where

$$C_{1} = \frac{4kT}{(2\pi)^{2}\rho} \left(\frac{\rho}{g}\right)^{3/2} \times \frac{5\Gamma(3-z)\Gamma(z-1) - 3\Gamma(z-1) - 15\Gamma(3-z)}{15\Gamma(3-z)\Gamma(z-1)}$$
(51)

and

$$C_2 = \frac{4kT}{(2\pi)^2 a\rho} \left(\frac{\rho}{\overline{g}}\right) \frac{1}{\Gamma(z-1)}.$$
(52)

Here, the dominant first term in Eq. (50) corresponds to a faster asymptotic decay of correlations for z < 1 than for simple liquids. This is a direct consequence of the superdiffusive propagation of stress in this case. Also, it is interesting to note that the second term in Eq. (50) strictly vanishes in the  $z \rightarrow 1$  limit of simple liquids.

#### **III. MATERIALS AND METHODS**

Simple liquids: For our experiments we used two Newtonian fluids with different viscosities  $\eta$  and mass densities  $\rho$ , namely, water ( $\eta$ =0.969 mPa s and  $\rho$ =1000 kg m<sup>-3</sup>) and a (1:1 v/v) water-glycerol mixture ( $\eta$ =6.9 mPa s and  $\rho$  =1150 kg m<sup>-3</sup>).

Viscoelastic fluids: We performed experiments with two different viscoelastic fluids, wormlike micelle solutions, and solutions of the cytoskeletal biopolymer F-actin. Wormlike micelles were prepared by self-assembly of cetylpyridinium chloride (CPyCl) in brine (0.5M NaCl) with sodium salicylate (NaSal) as counterions, with a molar ratio of Sal to CPy of 0.5. Three different concentrations of wormlike micelles were used:  $c_m = 0.5\%$ , 1%, and 2%. Wormlike micelles behave essentially like linear flexible polymers with an average diameter of about 3 nm, a persistence length of about 10 nm, and contour lengths of several micrometers [34]. F-actin was polymerized from monomeric actin (G-actin) isolated from rabbit skeletal muscle according to a standard recipe [35]. G-actin was mixed with silica beads in polymerization buffer [2 mM HEPES [4-(2-hydroxyethyl)-1piperazineethanesulfonic acid], 2 mM MgCl<sub>2</sub>, 50 mM KCl, 1 mM Na<sub>2</sub>ATP (adenosine-5'-triphosphate), and 1 mMEGTA (ethylene glycol tetraacetic acid), pH 7] and incubated for 1 h. Entangled actin solutions were used as a model system for semiflexible polymer solutions. Experiments were done at concentrations of c=0.5 and 1 mg/ml.

### A. Experimental methods

Details of the experimental setup can be found in [13,21,36,37]. Briefly, we have used a custom-built inverted microscope that includes a pair of optical traps formed by two focused laser beams of different wavelengths ( $\lambda$  = 1064 nm, Nd: YVO<sub>4</sub>, Compass, Coherent, Santa Clara, CA) and  $\lambda$ =830 nm (diode laser, cw, IQ1C140, Laser 2000). The optical traps fulfill two functions. (i) They confine the

particles around two well-defined positions and at the same time detect particle displacements with high temporal and spatial resolution in the passive method. (ii) In the active method one trap is used to apply a sinusoidally varying force to one particle, while the response of the other particle is detected in the second trap. In the passive method, a pair of silica beads (Van't Hoff Laboratory, Utrecht University, Utrecht, Netherlands) of various radii ( $R=0.25 \ \mu m \pm 5\%$ , 0.580  $\mu m \pm 5\%$ , 1.28  $\mu m \pm 5\%$ , and 2.5  $\mu m \pm 5\%$ ) were weakly trapped (trap stiffness between 2 and 5  $\mu$ N/m, where larger particles required the higher laser intensities to avoid shot noise. Transmitted laser light was imaged onto two quadrant photodiodes (QPD), such that particle displacements in the x and y directions were detected interferometrically [12]. A specialized silicon *p-i-n* photodiode (YAG444-4A, Perkin-Elmer, Vaudreuil, Canada), operated at a reverse bias of 110 V, was used in order to extend the frequency range up to 100 kHz for the 1064 nm laser [38]. The 830 nm laser was detected by a standard silicon p-i-n photodiode operated at a reverse bias of 15 V (Spot9-DMI, UDT, Hawthorne, CA). Amplified outputs were digitized at 195 kHz (analog-to-digital interface specs) and further processed in LABVIEW (National Instruments, Austin, TX). Output voltages were converted to actual displacements using Lorentzian fits to power spectral densities (PSDs) as described in [39]. In the case of water, calibration was done on the beads that were used in the experiments, while for the viscoelastic solutions and the more viscous liquid, calibrations were done in water with beads from the same batch.

In the active method, the 1064 nm laser was used to oscillate one particle, while the 830 nm laser was used for detection of the second particle at a separation distance r. The driving laser was deflected through an acousto-optical deflector (AOD) (TeO<sub>2</sub>, model DTD 276HB6, IntraAction, Bellwood, IL), using a voltage-controlled oscillator (DRF.40, AA Opto-electronic, Orsay, France). The force applied to the driven particle was calibrated by measuring the PSD of the Brownian motion of a particle of the same size trapped in water with the same laser power [39]. The output signal from the OPD detecting the second laser was fed into a lock-in amplifier (SR830, Stanford Research Systems, Sunnyvale, CA) to obtain the amplitude and phase of the particle response. All experiments were done in sample chambers made from a glass slide and a cover slip with about 140  $\mu$ m inner height, with the particles at least 25  $\mu$ m distance from both surfaces. The laboratory temperature was stabilized at T=21.5 °C.

## **IV. DATA ANALYSIS**

In both the active and passive methods, we calculate the linear complex response function  $\alpha$  defined by  $u(\omega) = \alpha(\omega)F(\omega)$ , where  $F(\omega)$  is the applied force. Linear response applies by definition in the passive method, and in the active method the particle displacements  $u(\omega)$  were kept sufficiently small. Again, we consider separately the real,  $\alpha'(\omega)$ , and imaginary parts,  $\alpha''(\omega)$ , of the response. In all our experiments, as sketched in Fig. 4, the coordinate system was chosen in such a way that *x* is parallel to the line connecting



FIG. 4. (Color online) Schematic sketch of the experiment. A pair of silica beads (radius *R*) is trapped by a pair of laser traps at a separation distance *r*. In the passive method, the position fluctuations of each particle in the *x* and *y* directions are simultaneously detected with quadrant photodiodes and the displacement cross correlations are measured parallel and perpendicular to the line connecting the centers of the two beads. In the active method, one of the beads is oscillated by rapidly moving one laser trap either in the *x* or in the *y* direction and the resulting motion of the other particle is measured in the *x* and the *y* direction. Laser intensity was adjusted to result in a trap stiffness typically between (2 and 5  $\mu$ N/m) for passive measurements.

the centers of the two particles (||) and y perpendicular  $(\perp)$  to that. The interparticle response functions along these two directions were used to determine the flow field.

The displacement  $u_x^{(1)}(\omega)$  of particle 1 in the *x* direction is related to the force  $F_x^{(2)}$  acting on particle 2 according to  $u_x^{(1)}(\omega) = \alpha_{\parallel}(\omega)F_x^{(2)}(\omega)$ . Similarly, the perpendicular response function was derived from  $u_y^{(1)}(\omega) = \alpha_{\perp}(\omega)F_y^{(2)}(\omega)$ . The single-particle response functions for each of the *x* and *y* directions are defined as  $u_{x,y}^{(1)}(\omega) = \alpha_{auto}(\omega)F_x^{(1)}(\omega)$ . For homogeneous, isotropic media, the two functions  $\alpha_{\parallel,\perp}(\omega)$  completely characterize the linear response at any point in the medium due to a force at another point. The displacement response functions  $\alpha_{\parallel,\perp}(\omega)$ .

In the passive approach, the medium fluctuates in equilibrium, and the only forces on the particles are thermal or Brownian forces. Therefore the fluctuation-dissipation theorem of statistical mechanics [40] relates the response of the medium to the displacement correlation functions. For two particles, these correlation functions are the cross-correlated displacement fluctuations  $\langle u_x^{(1)}(t)u_x^{(2)}(0)\rangle$  and  $\langle u_y^{(1)}(t)u_y^{(2)}(0)\rangle$ . We used fast Fourier transforms (FFT) to calculate displacement cross-correlation functions in frequency space and obtained the imaginary parts of the complex interparticle response functions  $\alpha''_{\parallel,\perp}(\omega)$  via the FDT:

$$\alpha_{\parallel}^{\prime\prime}(\omega) = \frac{\omega \int \langle u_x^{(1)}(t) u_x^{(2)}(0) \rangle e^{i\omega t} dt}{2kT}$$
(53)

and

$$\alpha_{\perp}^{\prime\prime}(\omega) = \frac{\omega \int \langle u_y^{(1)}(t) u_y^{(2)}(0) \rangle e^{i\omega t} dt}{2kT},$$
(54)

where *k* is the Boltzmann constant and *T* is the controlled laboratory temperature. The real parts of the interparticle response functions  $\alpha'_{\parallel,\perp}(\omega)$  were obtained by a Kramers-Kronig integral:

$$\alpha_{\parallel,\perp}'(\omega) = \frac{2}{\pi} P \int_0^\infty \frac{\zeta \alpha_{\parallel,\perp}''(\omega)}{\zeta^2 - \omega^2}$$
$$= \frac{2}{\pi} \int_0^\infty \cos(t\omega) \int_0^\infty \alpha_{\parallel,\perp}''(\zeta) \sin(t\zeta) d\zeta, \qquad (55)$$

where P denotes a principal-value integral [20]. The highfrequency cutoff of the Kramers-Kroning integral limits the frequency range of the calculated  $\alpha'_{\parallel,\perp}(\omega)$  [13]. We also used the active method to obtain both real and imaginary parts of the response functions with 100 kHz bandwidth, as in Refs. [21,37]. Here the lock-in amplifier provides directly the inphase (real part) and out-of-phase (imaginary part) responses of the second particle. The measurements were done over a grid of driving frequencies.

#### **V. RESULTS**

# A. Simple liquids

In the low-frequency limit, where fluid inertia can be neglected, the interparticle response functions are inversely related to the shear modulus of the medium [20,24,41]. For a simple viscous fluid, the response functions in this limit are given by

$$\alpha_{\parallel} = 2\alpha_{\perp} = \frac{i}{4\pi r \omega \eta},\tag{56}$$

where *r* is the separation distance between the two particles and  $\eta$  is the viscosity. These relations also shows (via the FDT) a 1/r dependence of the Fourier transform of the displacement cross-correlation functions:

$$S_{\parallel} = \int \langle u_x^{(1)}(t) u_x^{(2)}(0) \rangle e^{i\omega t} dt$$
(57)

and

$$S_{\perp} = \int \langle u_{y}^{(1)}(t)u_{y}^{(2)}(0) \rangle e^{i\omega t} dt.$$
 (58)

In Fig. 5, displacement cross-correlation functions for particle pairs in water, normalized to compensate for the distance dependence  $(4\pi rS_{\parallel} \text{ and } 8\pi rS_{\perp})$ , are plotted versus frequency. For comparison a single-particle displacement autocorrelation function, normalized for the bead size dependence  $(6\pi RS_{auto})$ , is plotted as a solid line, for a particle radius of  $R=0.58 \ \mu\text{m}$ . The autocorrelation function agrees well with the power-law slope of -2 up to nearly 100 kHz. This slope is expected from the high-frequency limit of the Lorentzian shape of the power spectral density (equal to the Fourier transform of the displacement autocorrelation function) of the displacements of a harmonically confined Brownian particle in a viscous fluid [39]. The effect of fluid inertia is evident as a deviation from this power law in



FIG. 5. Normalized displacement cross-correlation functions (a)  $4\pi rS_{\parallel}$  and (b)  $8\pi rS_{\perp}$  of two probe particles (silica beads,  $R = 0.58 \ \mu\text{m}$ ) in water versus frequency  $(f = \omega/2\pi)$ , compared for different separation distances r (symbols). In both (a) and (b), the solid line is the autocorrelation function of a single particle, normalized by  $6\pi R$ . The single-particle motion agrees well with the expected frequency dependence of a single Brownian particle (slope of -2), as indicated by the dashed lines.

the displacement cross-correlation functions. A systematic r-dependent decrease of the cross correlations is apparent at high frequencies for separations r ranging from 2.2 to 11.7  $\mu$ m. The faster decrease of cross correlations is a manifestation of the finite velocity at which stress propagates into the medium. For larger r, the data show that the decrease begins at a lower frequency, because it takes longer for stress to propagate further. A comparison of Figs. 5(a) and 5(b)shows that the decrease of the cross correlation is, at the same separation distance, more pronounced in the perpendicular channel than in the parallel channel. This is due to the fact that in the vortexlike flow pattern of Fig. 3 there is a region of fluid motion in the opposite direction to the applied force. For  $r > 5 \mu m$  (open squares), the cross correlations become negative in the observed frequency window (not shown in the log-log plot). At still higher frequencies, the displacement cross-correlation functions again become positive [Fig. 5(b)], which is visible for the larger separations r=8.3 and 11.7  $\mu$ m, consistent with the expected oscillation in the displacement cross-correlation functions in the frequency domain. This effect becomes more pronounced in viscoelastic media.

In both parallel (||) and especially perpendicular  $(\perp)$  correlation functions, the effects of inertia are readily apparent on the millisecond time scale for particle separations of ap-



FIG. 6. Normalized imaginary parts of interparticle response functions between two probe particles (silica beads,  $R=0.58 \ \mu\text{m}$ ) measured with the passive method, (a)  $4\pi r \eta \omega \alpha''_{\parallel}$  in the parallel direction and (b)  $8\pi r \eta \omega \alpha''_{\perp}$  in the perpendicular direction, plotted versus the ratio of the separation distance *r* (fixed for a given bead pair) to the frequency-dependent viscous penetration depth  $\delta_v$ , in water (open symbols,  $\eta=0.969 \ \text{mPa s}$ ) and in water-glycerol (filled symbols,  $\eta=6.9 \ \text{mPa s}$ ). Solid lines are Oseen's predictions for a simple liquid with no adjustable parameters. Data are plotted only for  $\omega > 200 \ \text{rad/s}$  and for  $\omega < 2 \ \text{krad/s}$ ; one in every five data points is shown.

proximately 10  $\mu$ m. This limits the high-frequency or shorttime range of validity of the analysis used previously in twoparticle microrheology [14–19,24]. The downturn in the data of Figs. 5(a) and 5(b) correspond to deviations from the 1/*r* dependence expected for instantaneous stress propagation. This limitation becomes increasingly severe at large separations *r*, due to the diffusive character of the stress propagation, which means, for instance, a loss of two decades in temporal resolution with each decade increase in particle separation. Similar limitations apply for viscoelastic media, as we show below.

The spatial and temporal propagation of the inertial vortex in a general viscoelastic medium is characterized by Eqs. (8)–(11) [4,7,11]. For simple liquids,  $A = \eta$  (viscosity) and z =1. In Figs. 6(a) and 6(b), we compare the imaginary parts of the normalized interparticle response functions  $4\pi\eta r\omega \alpha_{\parallel}^{"}(\omega)$  [Fig. 6(a)] and  $8\pi\eta r\omega \alpha_{\perp}^{"}(\omega)$  [Fig. 6(b)] for water and a (1:1 v/v) water-glycerol mixture. In order to collapse all data onto a single master curve, as suggested by Eqs. (8)–(11), we have plotted these normalized response functions versus the probe particle separation r scaled by the corresponding frequency-dependent penetration depth  $\delta_n$ 



FIG. 7. (Color online) Normalized imaginary parts of interparticle displacement response functions between two probe particles of various radii measured with the passive method in water (silica beads, *R* given in legend), (a)  $4\pi r \eta \omega \alpha''_{\parallel}$  in the parallel direction and (b)  $8\pi r \eta \omega \alpha''_{\perp}$  in the perpendicular direction, plotted versus the ratio of the separation distance *r* (fixed for a given bead pair) to the frequency-dependent viscous penetration depth  $\delta_v$ . These response functions also represent the in-phase velocity response normalized by the corresponding components of the Oseen tensor. Different particle sizes (*R*=0.58, 1.05, 1.28, and 2.5  $\mu$ m) were used at various separation distances *r*.

 $= \sqrt{\eta/\rho\omega}$ . As shown in Fig. 6, data taken at all of the different separations *r* ranging from 2.2 to 11.7  $\mu$ m fall onto a single curve for both the parallel [Fig. 6(a)] and the perpendicular [Fig. 6(b)] interparticle response functions. Data for water also collapse on the water-glycerol data, after accounting for the different viscosities, which are known in both cases. Thus, no free fit parameters were used. The single curves of collapsed data are in quantitative agreement with the frequency-dependent dynamic Oseen tensor in Eqs. (13) and (14) shown by the solid lines in Figs. 6(a) and 6(b), where the region of negative response in the perpendicular direction corresponds again to the backflow region of the vortex already described above.

At separations *r* large compared to particle size, the interparticle response functions become independent of probe particle size and shape [24], leaving a dependence only on *r* and  $\omega$ . In our analysis, we have assumed that the particles are pointlike since the ratio  $r/R \ge 4$  in all experiments. In order to directly check the validity of the approximation, we measured the interparticle response functions with particles of different sizes. In Figs. 7(a) and 7(b) the imaginary parts of the normalized response functions in water  $4\pi \eta r \omega \alpha_{\parallel}^{"}(\omega)$  and  $8\pi\eta r\omega \alpha''_{\perp}(\omega)$  are plotted versus  $r/\delta_v$ , obtained with probe particles of radius R=0.58, 1.05, 1.28, and 2.5  $\mu$ m. We find no systematic bead-size dependence, justifying the pointprobe approximation. Again all normalized and scaled data collapse onto one single curve for each channel, which in turn agrees well with the dynamic Oseen tensor. The deviations observed in the last data points for R=1.05 and 2.5  $\mu$ m are most probably due to the influence of shot noise at high frequencies. Shot noise becomes a problem for larger beads because of their smaller fluctuation amplitudes, which will eventually produce signals that approach the fixed shot noise level. The deviations observed for these particle sizes are not consistent with a possible error due to finite particle size, which should be larger for smaller r/R.

So far, we have considered the passive fluctuations that directly measure only the imaginary (out-of-phase) part of the interparticle response functions  $[\alpha''_{\parallel,\perp}(\omega)]$ . With the active method described in Sec. III A we can determine both real and imaginary part of the response functions. In Figs. 1(a) and 1(b), we show the normalized inter-particle response functions  $\alpha'_{\parallel,\perp}(\omega)$  and  $\alpha''_{\parallel,\perp}(\omega)$  measured by active microrheology (bead radius R=0.58  $\mu$ m) in water for both parallel and perpendicular directions. In both cases we find good agreement with Eqs. (13) and (14). The slightly different separation distances in parallel (r=10.3  $\mu$ m) and perpendicular (r=11.3  $\mu$ m) directions were due to different settings of the AOD signal in these measurements.

#### **B.** Viscoelastic solutions

In viscoelastic polymer solutions, the elastic component in the response of the medium modifies the propagation of the inertial vortex. We first discuss our results for wormlike micelle solutions, the viscoelastic properties of which have been characterized by microrheology [42,43]. In Fig. 8 we have plotted the displacement cross-correlation functions  $(4\pi rS_{\parallel} \text{ and } 8\pi rS_{\perp})$  in a 1% wormlike micelle solution versus frequency for two particles at various separation distances rbetween 2 and 8  $\mu$ m. For comparison, we have added the scaled autocorrelation function  $6\pi RS_{auto}$  for a single particle  $(R=0.58 \ \mu m)$ . In contrast to the situation in simple liquids, the particles were here confined by the surrounding polymer network and do not diffuse freely. Thus, the frequency dependence is weaker than for Brownian motion (i.e., the slope is less steep than -2 in the low-frequency, noninertial regime) [42,43]. As before, the displacement cross-correlation functions of the two probe particles are used to map the vortexlike flow pattern and its propagation in time. The r-dependent decrease of the cross-correlation functions occurs for both parallel [Fig. 8(a)] and perpendicular [Fig. 8(b)] directions, although the latter is more apparent.

In order to collapse these data onto a single curve for each of the two channels (parallel and perpendicular), following Eqs. (8)–(11), we plot the normalized interparticle response functions  $4\pi |G| r \alpha_{\parallel}''$  and  $8\pi |G| r \alpha_{\perp}''$  versus scaled  $r/\delta_{ve}$ , where  $\delta_{ve}$  is the viscoelastic penetration depth. Unlike for the water and water-glycerol samples, we do not *a priori* know the frequency-dependent shear modulus  $G^*(\omega)$ . Based on theoretical expectations for flexible polymers [27], as well as



FIG. 8. Normalized displacement cross-correlation functions  $4\pi rS_{\parallel}$  (a) and  $8\pi rS_{\perp}$  (b) of two probe particles (silica beads,  $R = 0.58 \ \mu\text{m}$ ) in worm-like micelle solutions ( $c_m = 1 \ \text{wt \%}$ ) versus frequency ( $f = \omega/2\pi$ ) compared for different separation distances r. The solid lines represent the autocorrelation function of a single particle normalized by  $6\pi R$ . The dashed lines indicate slopes of -2, corresponding to diffusive motion.

on prior high-frequency rheology of wormlike micelle solutions [42,43], we assume that the shear modulus has the functional form given in Eq. (22). Thus, in order to achieve the collapse of all data onto the master curves represented by Eqs. (8)–(11), we vary the two correlated parameters  $\overline{g}$  and z. We expect z to be independent of the micelle concentration, while  $\overline{g}$  should depend linearly on the polymer or micelle concentration. In Fig. 9(a), we show the resulting collapse of the normalized interparticle response functions in parallel and perpendicular directions for different separations r. The predictions of Eqs. (8)–(11) are shown with black and gray lines [11]. The best overall collapse of the data for wormlike micelle solutions at all concentrations (0.5, 1, and 2 wt %)and separations r from 2 to 16  $\mu$ m was found for z =0.68  $\pm$  0.05 and  $\overline{g}$  concentration dependence as seen in Fig. 9(b).

In order to further test the inertial effects in viscoelastic media, we also performed experiments on another viscoelastic fluid with a somewhat different frequency-dependent shear modulus, namely, entangled F-actin solutions. At high frequency, semiflexible F-actin filaments contribute to the viscoelasticity of the medium in a different way from flexible polymers [19,20,28,29]. Therefore, the spatial structure and the propagation dynamics of the vortex should be different. Figure 10 shows the collapse of the interparticle response



FIG. 9. (Color online) (a) Collapse of the dimensionless interparticle response functions  $4\pi r |G| \alpha''_{\parallel}$  and  $8\pi r |G| \alpha''_{\parallel}$  versus nondimensionalized distance  $r/\delta_{ve}$  between silica probe particles of radius  $R=0.58 \ \mu m$ . These measurements were performed on wormlike micelle solutions of 1 wt %, using the passive method. Here, the viscoelastic penetration depth  $\delta_{ve}$  depends on the parameters  $\overline{g}$  and z via Eqs. (12) and (22), and these parameters were adjusted to obtain the best collapse. Optimal parameters were z=0.68  $\pm$  0.05 and  $\overline{g}$ =0.0275  $\pm$  0.008 Pa s<sup>z</sup>, where the solvent (water) viscosity was also taken into account via Eq. (22). (b) The dependence of  $\overline{g}$  on micelle concentration was determined by finding the best simultaneous fits or collapse of the data for a range of r values and for different concentrations, using a fixed value of z=0.68. The error bars were estimated by the range of  $\overline{g}$  yielding data collapse. The resulting concentration dependence confirms the expected linear behavior.

functions  $4\pi |G| r \alpha_{\parallel}^{"}$  and  $8\pi |G| r \alpha_{\perp}^{"}$  plotted versus scaled distance  $r/\delta_{ve}$  onto two master curves for the parallel and the perpendicular direction. The actin concentration was 1 mg/ml and the probe radius 0.58  $\mu$ m and we used separation distances r ranging from 4.2 to 16.2  $\mu$ m. In an F-actin solution of this concentration, the magnitude of the shear modulus is large, therefore the vortex propagates faster, making it harder to observe. In particular, it was difficult to determine the parameters  $\overline{g}$  and z in this case. We found the best collapse with  $z=0.78\pm0.1$  for data taken in passive method. We then fixed z to 0.75 known from the power-law dependence behavior reported previously [19,20,28,29], and found  $\overline{g}=0.18\pm0.13$  Pa s<sup>z</sup>. To reduce the large error bars in the passive method, it would be necessary to repeat our measurements at higher frequencies and/or larger separation dis-



FIG. 10. (Color online) Collapse of the imaginary parts of the normalized interparticle response functions between two probe particles (silica beads,  $R=0.58 \ \mu\text{m}$ ), measured with the passive method for different separation distances *r* in F-actin solutions of concentration 1 mg/ml, plotted versus the ratio of the separation distance *r* (fixed for a given bead pair) to the frequency-dependent viscoelastic penetration depth  $\delta_{ve}$ . Here, the parameters  $\overline{g}$  and *z* in Eq. (22) were varied to obtain simultaneous collapse of all data sets onto Eqs. (8)–(11), using a single set of parameters *z* and  $\overline{g}$ , while accounting for the solvent (water) viscosity. We find  $z=0.78\pm0.13$  and  $\overline{g}=0.18\pm0.134$  as optimal parameters. Data are presented for parallel (closed symbols) and perpendicular (open symbols) directions. The solid black line represents Eq. (29) and the gray line represents Eq. (31), both with z=0.75 and  $\overline{g}=0.2$  Pa s<sup>z</sup>.

tances. Nevertheless, our results are consistent with prior measurements and predictions of both parameters.

Independently, we have measured both real,  $\alpha'_{\parallel,\perp}(\omega)$ , and imaginary,  $\alpha''_{\parallel,\perp}(\omega)$ , parts of the response functions directly by actively manipulating one particle and measuring the response of the other. In Figs. 2(a) and 2(b), the parallel [Fig. 2(a)] and perpendicular [Fig. 2(b)] complex interparticle response functions for c=1 mg/ml F-actin solutions are shown, probed with beads of 1.28  $\mu$ m radius. Here the interparticle response functions were fitted with Eqs. (8)–(11) to find the parameters  $\bar{g}=0.22\pm0.05$  Pa s<sup>z</sup> and z =0.78±0.01 simultaneously. Data for both parallel (r=12.1  $\mu$ m) and perpendicular ( $r=13.5 \mu$ m) channels are compared with z=0.75 and  $\bar{g}=0.22$  Pa s<sup>z</sup> in Figs. 2(a) and 2(b).

The values of z and  $\overline{g}$  found from both methods are consistent and also agree with results from prior experimental microrhelogy and macrorheology experiments for both entangled actin solutions [18–20,28,29] and wormlike-micelle solutions [42,43]. To obtain these values it was essential to model the inertial effects including both polymer and solvent contributions to the shear modulus. We observed that, although the high-frequency rheology of the polymer solution is dominated by the polymer, the background solvent contributes non-negligibly to the inertial vortex propagation. To test this, we excluded the solvent shear modulus  $(-i\omega\eta)$  in Eqs. (8)–(11) and (22), and analyzed our data assuming a high-frequency shear modulus of the form  $G=\overline{g}\omega^z$ . For both wormlike micelle solutions and entangled F-actin solutions,

we found much larger values of  $z \sim 0.9$  and a nonlinear concentration dependence of  $\overline{g}$ , contrary to expectations.

## VI. DISCUSSION

In our experiments we have directly resolved the inertial response and flow of fluids on micrometer and microsecond time scales using optical trapping and interferometric particle tracking. Our results demonstrate that vorticity and stress propagate diffusively in simple liquids and superdiffusively in viscoelastic media. One consequence of inertial vortex formation is the long-time tail effect observed in light scattering experiments [6]. To connect to these results, we calculated the velocity autocorrelation of a single particle from the displacement fluctuations. Unfortunately, the effect we are looking for is subtle and is difficult to detect in the presence of other factors. At the highest frequencies the vortex is still influenced by the finite probe size, and at intermediate frequencies the particle motion is already affected by the laser trap potential. The results were thus inconclusive. Similar problems have been reported in Ref. [9]. The effects of inertia we have described here set a fundamental limit to the applicability of two-particle microrheology techniques which are based on the measurement of cross-correlated position fluctuations of particles [14,18,19,24,42]. Inertia limits the range of stress propagation at high frequencies, stronger in soft media such as those studied here than in media with higher viscoelastic moduli. Inertia affects measurements at frequencies as low as 1 kHz for separations of order 10  $\mu$ m, showing an apparent increase of the measured shear moduli below their actual values [43]. Since the stress propagation is diffusive, or nearly so, even measurements at video rates can be affected for probe particle separations of order 50  $\mu$ m. As we have shown here, these inertial effects are more pronounced in the perpendicular interparticle response functions than in the parallel ones. This suggests that one should obtain shear moduli from the parallel inter-particle response functions if one does not want to correct for inertia. In a more precise analysis of two-particle microrheology experiments, the fluid response function cannot simply be modeled by a generalized Stokes-Einstein relationship and has to be corrected for inertial effects according to the probed frequency as well as the particles separation. Such corrections, however, will necessarily be limited, given the exponential attenuation of stress due to inertia.

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